
```

set(0,'DefaultAxesLinewidth',2,'DefaultLineLineWidth',2);
set(0,'defaultAxesFontSize',14);
set(0,'defaultAxesFontName','arial');
set(0,'defaultTextFontName','arial');

close all
clear

A = [0 1 0;0 0 1;-0.5 -0.4 -0.3];

B = [0;0;1];
C = [1 1 0];

setlmis([])

[P,n,sP] = lmivar(1,[3 1]);

S1 = newlmi;
lmiterm([S1 1 1 P],A',A)
lmiterm([S1 1 1 P],[-1,1)
lmiterm([S1 1 1 0],eye(3,3))
lmiterm([-S1 2 2 P],1,1)
LMIs = getlmis;
c = [1 0 0 0 0 0];

%[tmin,xopt] = feasp(LMIs);

[copt,xopt] = mincx(LMIs,c);

P1 = dec2mat(LMIs,xopt,P)

%A'*P1*A-P1+eye(3,3)
%eig(ans)

Solver for linear objective minimization under LMI constraints

Iterations      :      Best objective value so far

      1
      2
      3
***      new lower bound:      1.494135
      4
***      new lower bound:      1.772354
      5
***      new lower bound:      1.944421
      6
***      new lower bound:      2.104946
      7
***      new lower bound:      2.116536

```

Result: *feasible solution of required accuracy*
best objective value: 2.136836
guaranteed relative accuracy: 9.50e-03
f-radius saturation: 0.000% of R = 1.00e+09

P1 =

2.1368	0.7957	0.2274
0.7957	3.6827	0.9093
0.2274	0.9093	4.5468

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